

# PID 가?

PID (Proportional), (Integral), (Derivative) 가 (Set-Point) 가 PID (Cruise Control) 가 (Thermostat)

$$( ) = ( ) - ( )$$

PID

PID 가

- P Proportional Ban = 100/gain
- I Integral = 1/reset(units of time)
- D Derivative = rate = pre-act(units of time)

integral reset action  
 time/repeat repeat/time  
 가  
 time/repeat reset  
 repeat/time integral  
 Derivative rate

Proportional Band

Proportional

$$( ) = ( ) * 100 / (\text{Proportional band})$$

Proportional controller offset(set-point) gain 가 loop Integral action offset

Integral

Integral

Integral

offset

CONTROLLER OUTPUT

$$= (1/\text{INTEGRAL}) (\text{Integral of } e(t) dt)$$

1

offset ( )

가

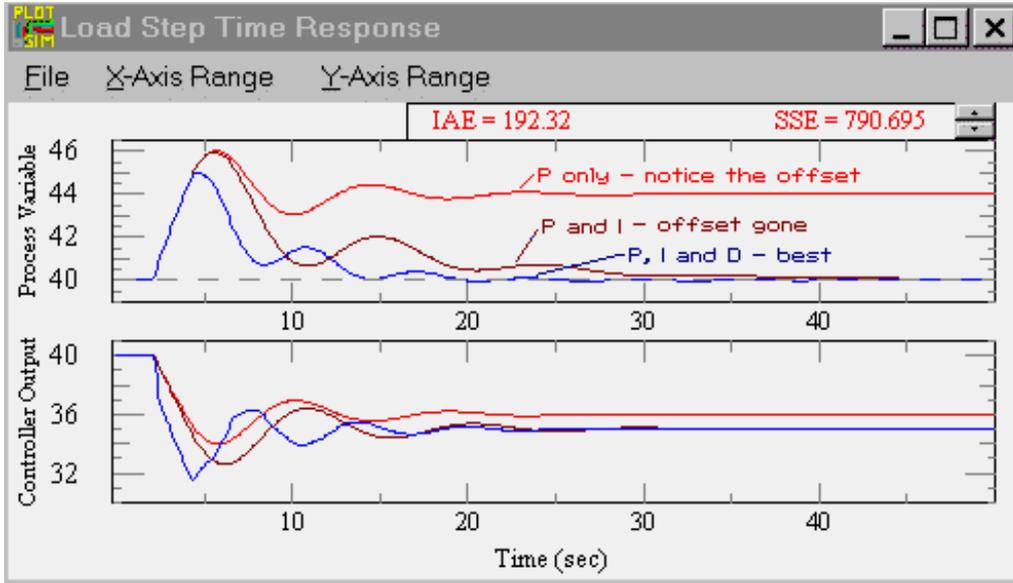
derivative 가 (Graphic courtesy of ExperTune Loop Simulator)

Derivative

Derivative

CONTROLLER OUTPUT =

$$\text{DERIVATIVE } \frac{dm}{dt}$$



1

m t . ratio가

Integral 가

derivative pre-act gain derivative “dip”

term rate . Derivative

derivative

(314 radians/time :

DERIVATIVE = RATE = PRE ACT Nyquist frequency)

amplitude ratio 가 bit

Derivative sampling

. Proportional 가 가

. load amplitude ratio Nyquist

가 frequency

derivative PI

가 . Derivative loop

. Derivative

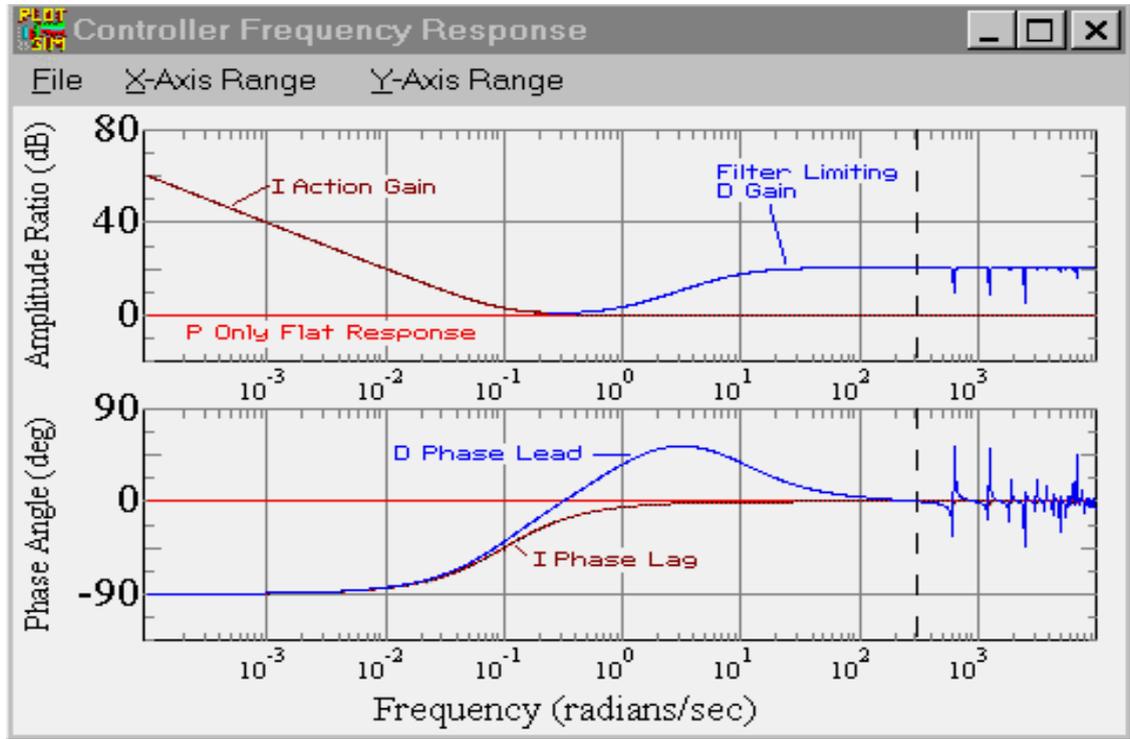
Control Loop Tuning

Derivative lead가

loop loop

가

2 PID amplitude .



2

trim 가 .  
 가 .  
 5% 10%  
 loop loop 가 .  
 가 가  
 P Proportional Band , I  
 time/repeat P 가 가

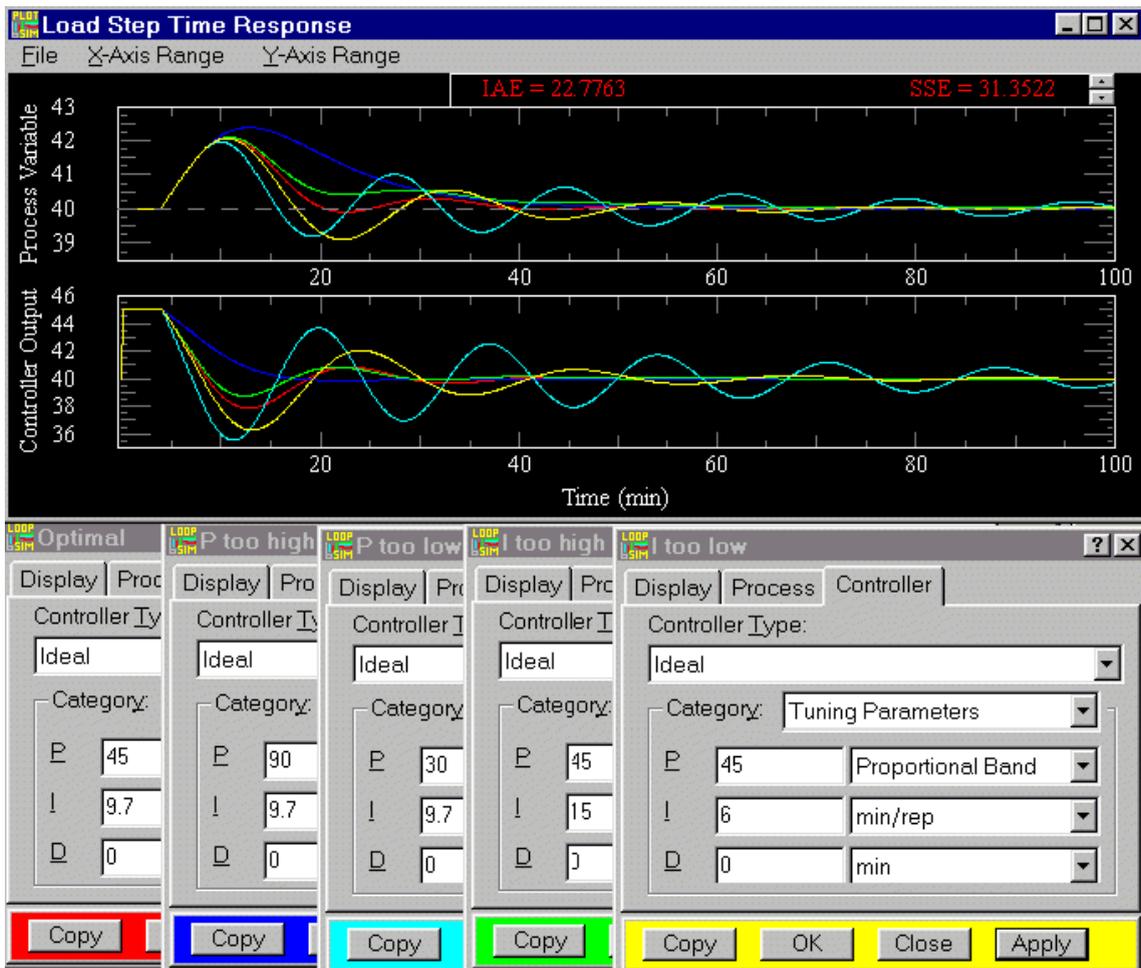
Fine Tuning "Rules"

Loop Simulator 3 PI  
 I P PID

dead time 4, lag time 10 .

.(가 4  
 가 )

I P가



3

Loop Type	PB %	Integral min/rep	Integral rep/min	Derivative min	Valve type
Flow	50 to 500	.005 to .05	20 to 200	none	Linear or Modified Percentage
Liquid Pressure	50 to 500	.005 to .05	20 to 200	none	Linear or Modified Percentage
Gas Pressure	1 to 50	.1 to 50	.02 to 10	.02 to .1	Linear
Liquid Level	1 to 50	1 to 100	.01 to 1	.01 to .05	Linear or Modified Percentage
Temperature	2 to 100	.2 to 50	.02 to 5	.1 to 20	Equal Percentage
Chromatograph	100 to 2000	10 to 120	.008 to .1	.1 to 20	Linear

4